

Unification of height systems in the frame of GGOS

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Motivation

GGOS requires *a global gravity field-related height frame* with

- an *order of accuracy higher* than the magnitude of the phenomena to be observed (e.g. global change);
- consistency and reliability worldwide (*the same accuracy everywhere*);
- long-term stability (*the same accuracy at any time*).

The *existing height systems* exhibit

- more than *100 realizations* with *discrepancies up to dm ... m*;
- *static heights* $\rightarrow \dot{H} \equiv 0$ and *imprecise combination* with geometric heights
 $|h - H - N| \rightarrow \gg 0$;
- *1 ... 2 order of accuracy less* than the ITRS/ITRF coordinates.

However, these heights systems

- are the *reference* for the heights determined *in the last 150 years*;
- provide a *higher accuracy in contiguous areas* than the combination of ellipsoidal heights with (quasi-)geoid models, i.e. $H=h-N$.

If these systems are integrated into the global height system, *the existing vertical data can be updated and be useful for GGOS*.

Basics to establish a global vertical reference system

Main requirement: consistent combination of ellipsoidal and physical heights

$h - H^N - \zeta \approx h - H - N \rightarrow 0$ with high accuracy (mm ... cm) worldwide

Geometrical component

Definition:

Coordinates: $h(\mathbf{X}, t); dh(\mathbf{X})/dt$

Reference level: $U_0 = U(\mathbf{X}) = const.$

Realization:

- 1) referred to the ITRS/ITRF
- 2) conventional ellipsoid



Alignment of standards and conventions to guarantee the consistency between physical and geometrical parameters.



Physical component

Definition:

Coordinates: $C(\mathbf{X}, t) = W_0 - W(\mathbf{X}, t); dC(\mathbf{X})/dt$

Reference level: $W(\mathbf{X}) = W_0 = const.$

Realization:

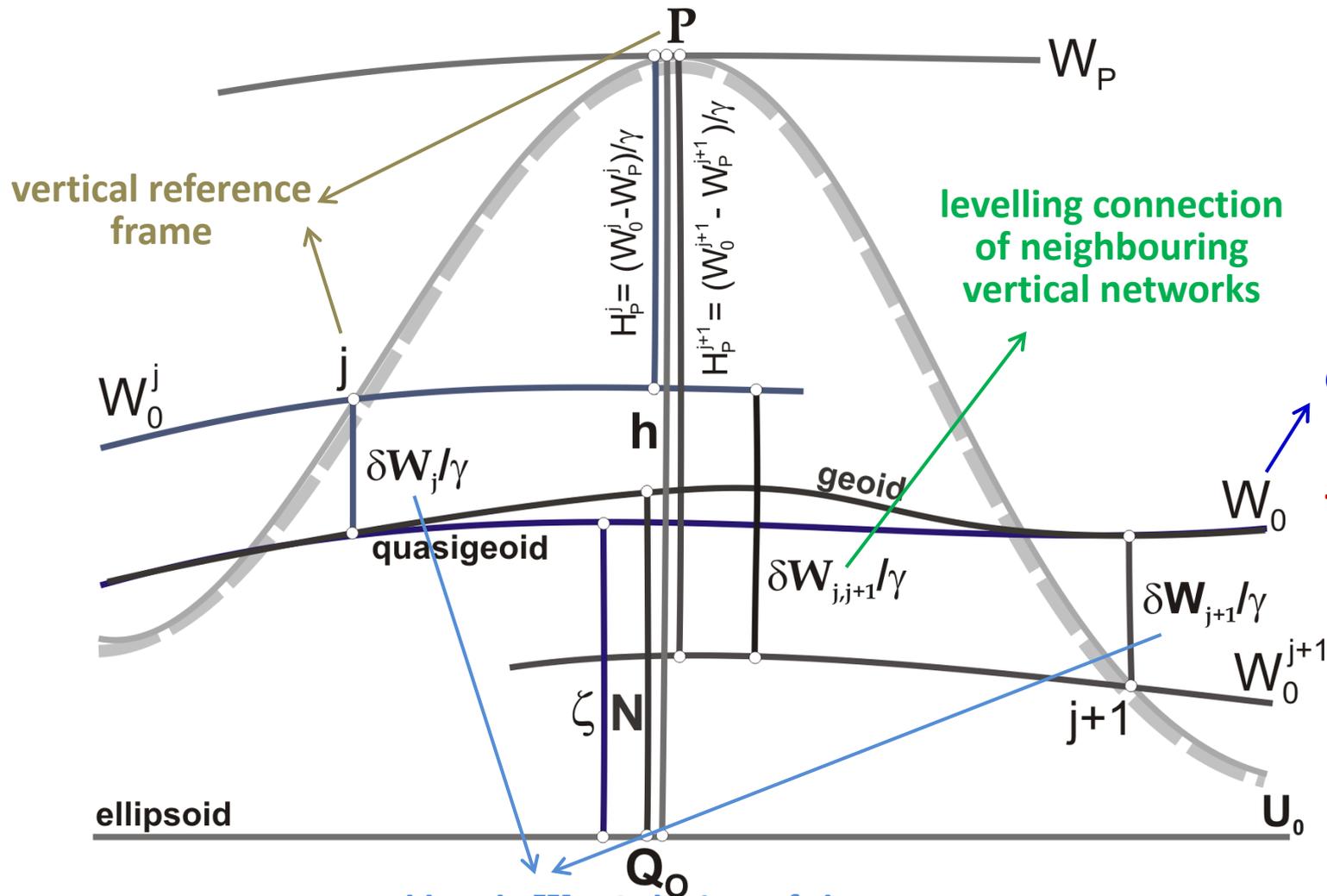
- 1) Adoption of a suitable W_0 value;
- 2) Realization of the reference surface defined by W_0 (i.e. geoid modelling);
- 3) Connection of the local reference levels with the global one $\delta W_0^i = W_0 - W_0^i$ (i.e. vertical datum unification based on geopotential numbers);
- 4) Conversion into physical heights (H, H^N, \dots)

Remarks on the vertical reference level W_0

- It is to be *defined arbitrarily by convention* (like any reference system);
- Basic convention:
 - 1) *Reference level*: potential value W_0 defining *the scale* of the global zero-height surface;
 - 2) *Reference surface*: realization (geometric description) of the surface with the potential value W_0 (e.g. *geoid computation*);
- To get consistency between definition (W_0) and realization (geoid modelling), W_0 shall be *estimated from the same observations applied for the geoid modelling*;
 - 1) *Global reference level W_0* : by solving the *fixed GBVP on ocean areas*
 - 2) *Local reference levels W_0^i* : by solving the *Molodenskii scalar-free GBVP on land areas* (vertical datum unification)
- Most appropriate W_0 value according to the *GGOS Working Group on Vertical Datum Standardization*:

$$W_0 = 62\,636\,853,4 \text{ m}^2\text{s}^{-2}$$

Remarks on the vertical reference level W_0



Global W_0 : Solution of the fixed GBVP on ocean areas. To be introduced as IAG convention

Local levels W_{0i} : Solution of the scalar-free GBVP on land areas (vertical datum unification).

Realization in practice: vertical reference frame

- Like the ITRF: A *global network* with *regional/national densifications*.
- This network shall include:
 - 1) *reference tide gauges* (local vertical datum points);
 - 2) main *nodal points of the levelling networks*;
 - 3) geometrical reference stations (*ITRF* and densifications);
 - 4) fundamental *geodetic observatories* (connection between W_0 and TAI).
- These stations must be:
 - 1) *continuously monitored* to detect deformations of the reference frame;
 - 2) *referred to the ITRS/ITRF* to precisely know their geometric coordinates;
 - 3) *connected by levelling with the local vertical datum* to precisely know their local geopotential numbers.

Observation equations for the vertical datum unification

(after Rummel und Teunissen 1988, Heck and Rummel 1990)

- at border points connecting neighbouring vertical datum zones:

$$H^{N,i+1}(P) - H^{N,i}(P) = q(\delta W_0^{i+1} - \delta W_0^i)$$

- at tide gauges, levelling nodes, geometric reference stations

$$h(P) - H^{N,i}(P) - q\Delta W_0 - E(\zeta(P)) = e^i(P)\delta W_0^i + \underbrace{\sum_{\substack{j=1 \\ i \neq j}}^J f_0^j(P)\delta W_0^j(P)}_{\text{indirect effects (negligible)}}$$

GNSS positioning on land and satellite altimetry on sea areas around tide gauges

heights from geop. numbers on land and sea surface topography around tide gauges

$$\Delta W_0 = W_0 - U_0$$

height anomalies from GBVP [GGM (n=200) + terrestrial gravity + terrain models]

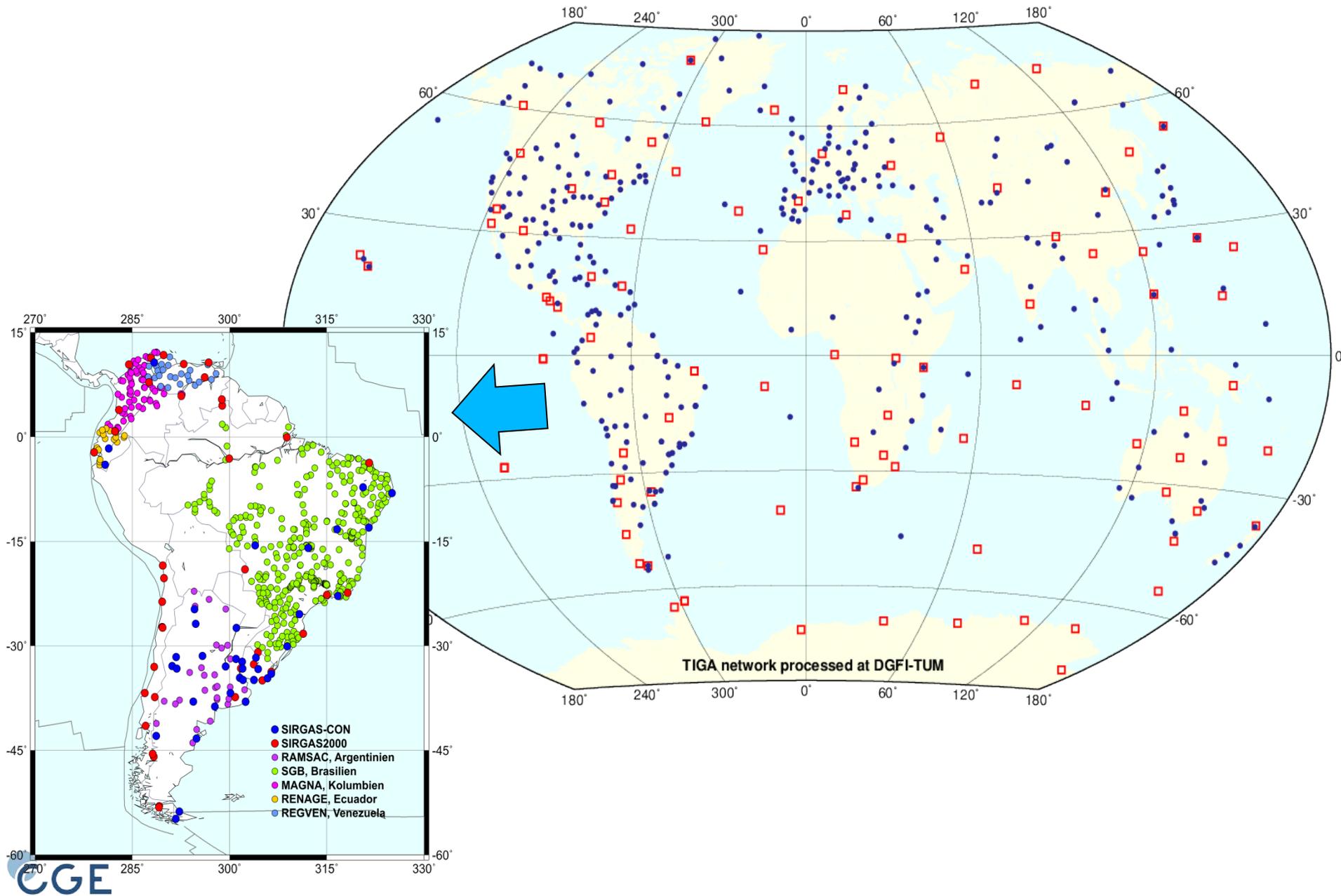
vertical datum discrepancies (to be determined)

indirect effects (negligible)

$$q := -\frac{1}{\gamma}, \quad e^i(P) := -q + f_0^i(P), \quad f_0^i(P) := \frac{1}{2\pi\gamma} \iint_{\sigma_i} S(\psi_{P,P_k}) d\sigma$$

Example: a global vertical reference frame with regional densifications (e. g. South America)

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Example: vertical datum unification in South America

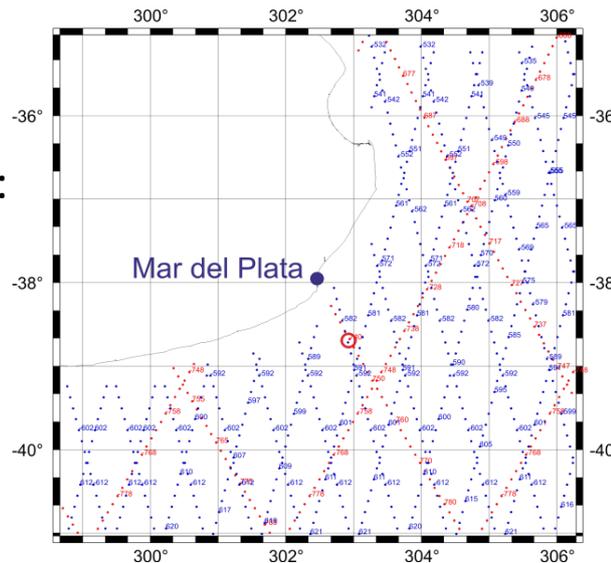


Existing height systems

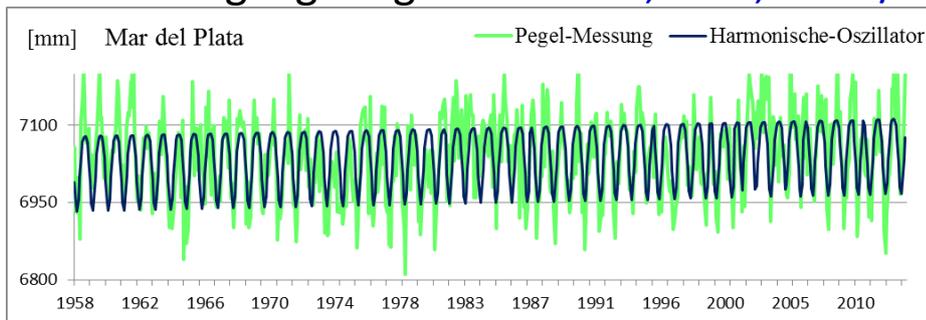
- 15 reference tide gauges;
- mean sea surface level referred to a *different epochs* (some unknown);
- Levelling *since ~1940* with $dH/dt = 0$;
- in general *no gravity reductions applied*;
- *no common adjustment*;
- First and second order levelling networks comprise more than *360 000 km* and *200 000 bench marks*.

Example: vertical datum unification in South America

Trend from satellite altimetry:
 $2,4 \pm 0,8 \text{ mm/a}$



Trend from gauge registrations: $0,6 \pm 0,2 \text{ mm/a}$



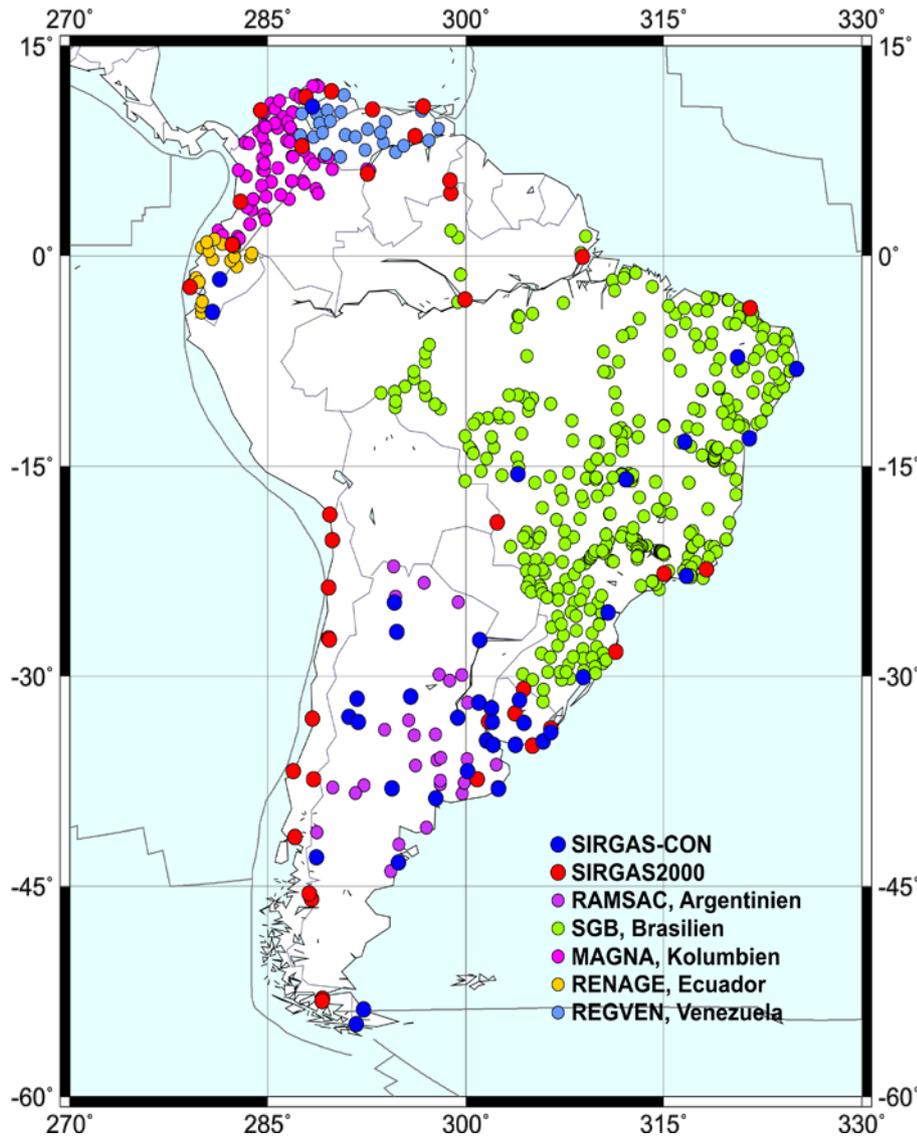
Trend from GPS: $2,2 \pm 2,2 \text{ mm/a}$

→ Discrepancy: $2,4 - (2,2 + 0,6) = 0,8 \text{ mm/a}$

Geometric heights in sea areas around tide gauges

- mean sea surface heights from satellite altimetry (OpenADB);
- Tide gauge registrations from PSMSL;
- GNSS positioning at tide gauges.
- *Data standardization* (TIGA objectives):
 - Determination of *vertical trends* from satellite altimetry, tide gauge registrations, and GPS;
 - It is assumed that the trends $(dh/dt)_{\text{Altimetry}} = (dh/dt)_{(\text{Gauge} + \text{GPS})}$
 - Reduction of the reference sea levels to a common *epoch* (2005.0).

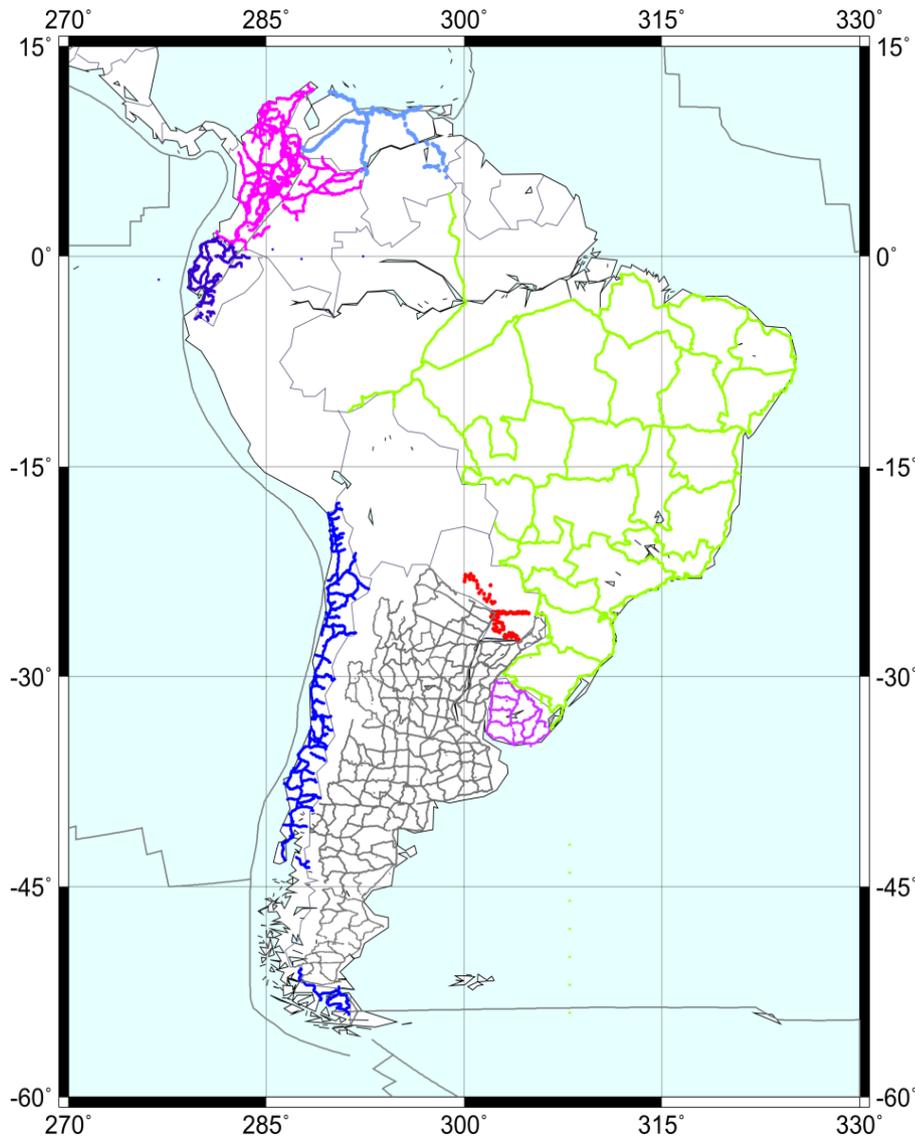
Example: vertical datum unification in South America



Geometrical heights on land areas

- Reference stations (663):
ITRF stations (10) +
SIRGAS stations (74) +
national densifications (579);
- Data standardization:
 - Transformation of previous ITRF solutions to the IGB08;
 - Stations positions given at a *common epoch (2005.0)* (with station velocities or a kinematics model - VEMOS);
 - Transformation *from conventional tide-free to zero-tide*.

Example: vertical datum unification in South America



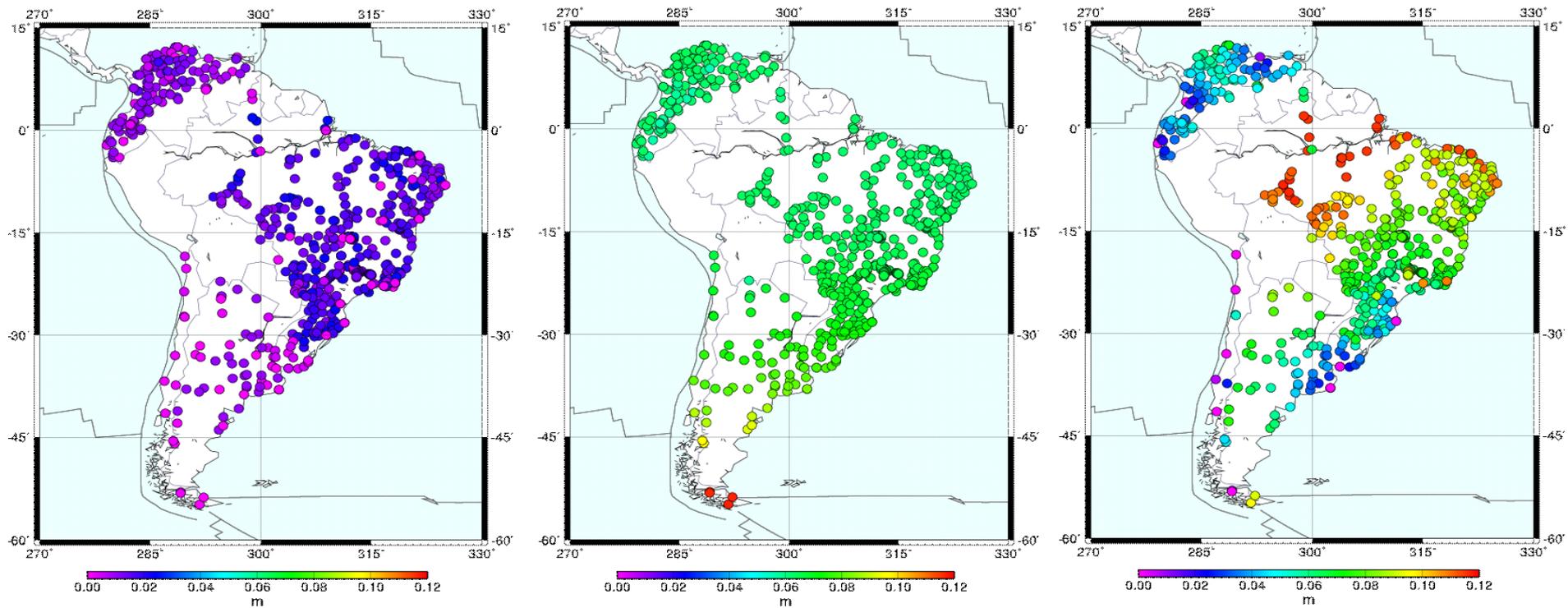
Observed height differences

- Levelling lines provided by the countries
- Data standardization:
 - least squares adjustment country by country to build *free normal equations for each vertical datum zone*;
 - astronomical correction + indirect effect (levelling in *zero-tide system*);
 - *kinematic adjustment* assuming $dH/dt \approx dh/dt$;
 - *combination of free normal equations* for countries with international levelling connections

Example: vertical datum unification in South America

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Uncertainty of the input data



Ellipsoidal heights

Height anomalies

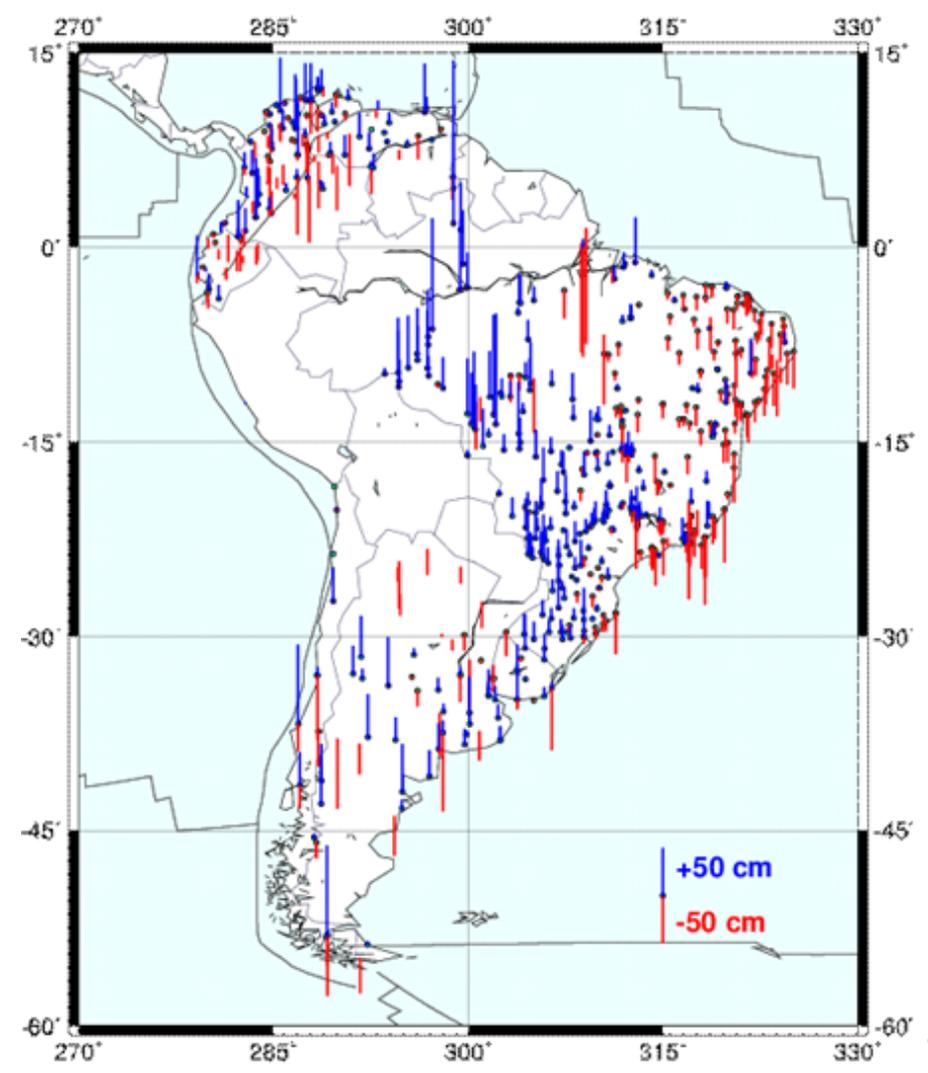
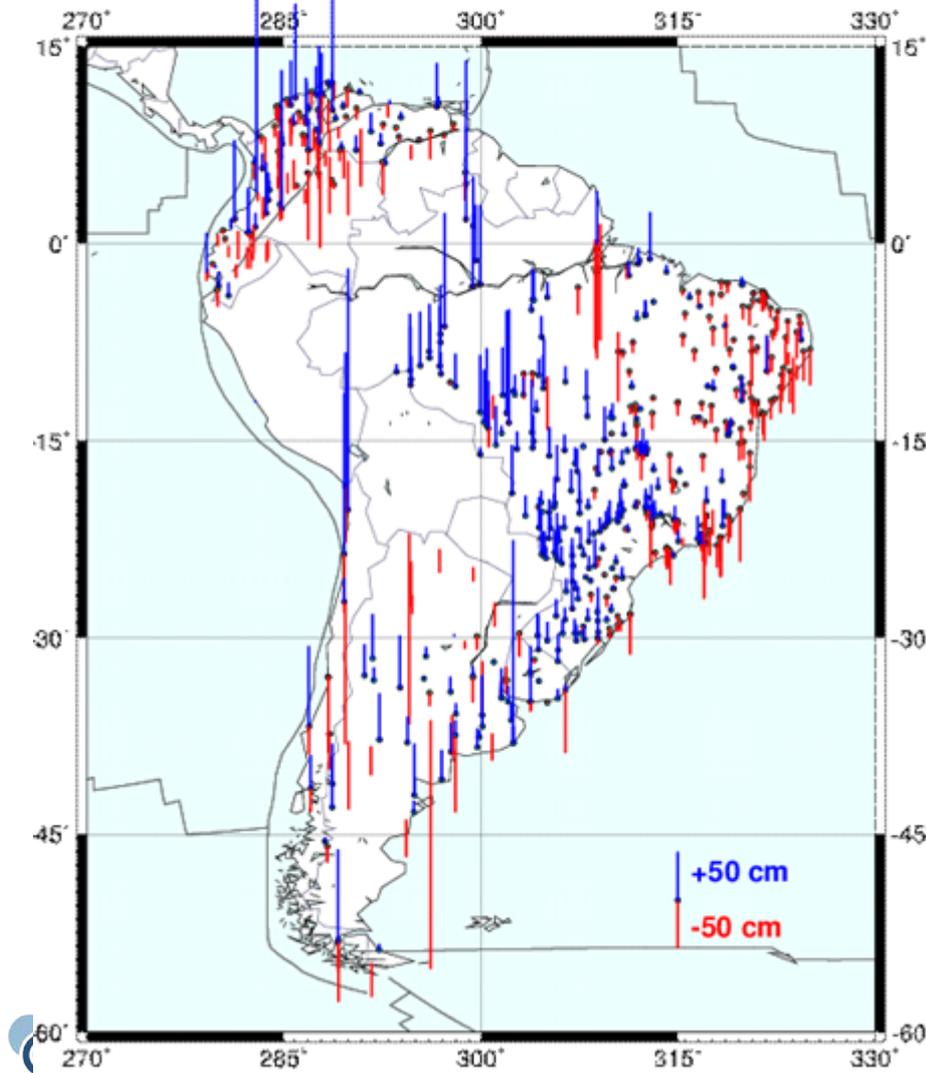
Normal heights

Example: vertical datum unification in South America

Residuals

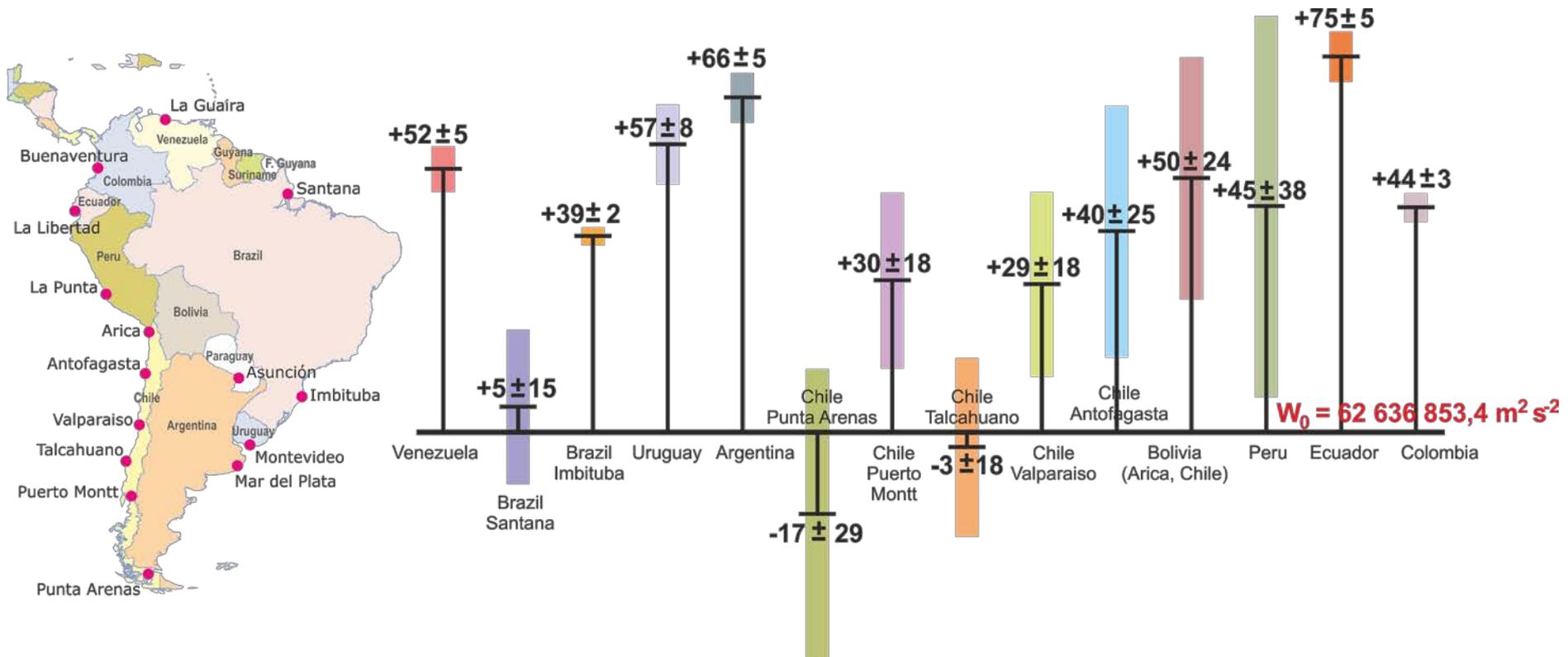
with input data as they are

with input data standardized



Example: vertical datum unification in South America

Vertical datum parameters with respect to $W_0 = 62\,636\,853,4 \text{ m}^2\text{s}^{-2}$



- Uncertainty of about ± 5 cm in those countries with *good data coverage*;
- Uncertainty of about $\pm 20 \dots 40$ cm in those countries with *poor data coverage* (similar uncertainties have been found by other authors in other regions, e.g. Gruber et al. 2012 Rülke et al. 2014, Gerlach and Rummel 2013)

Closing remarks

- A global vertical reference system shall support the *unification of the existing height systems* in order *to be accepted and used worldwide*;
- The vertical datum unification requires essentially *levelling-based geopotential numbers* and *(quasi)-geoid models of high-resolution*;
- The precise combination of physical heights, ellipsoidal heights and (quasi-)geoid models requires *a standardization* of conventions, constants, and procedures (e.g. *tide system, reference epoch for vertical positions, etc.*).
- The establishment of a global unified vertical reference system of high-precision *is only possible under the umbrella of the IAG, GGOS and its services*.